

Support Your Motion



Application of **MUSCLE SUIT** to Nursing Care & Functional Training

INNOVTION + **PHYSICAL** + SUPPORT

生きている限り自立した生活を。

 **INNOPHYS** Co., Ltd. Founder
Tokyo Univ. of Science, Professor

Dr. Hiroshi Kobayashi

The beginning of the concept of robots



紀元前8世紀

ギリシアの詩人ホメロス、
世界最古の叙事詩『イーリアス』

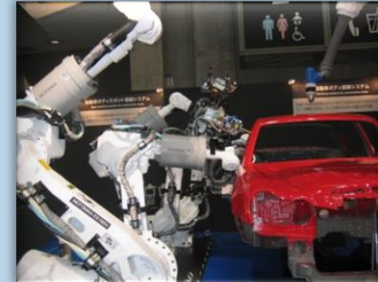
8th century BC
Greek poet Homer,
The world's oldest epic "Iliad"



Background



Transport Technology

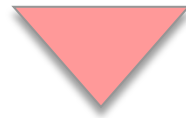


Industrial Robots

Release the man from hard labor

Mechanical system paradigm shift

~20th century (free from **physical** burden)
works hard instead of humans



21st century (free from **mental** burden)
maintains & supports independence



Goal

whoever lives can live independently.

If you don't have to worry about being bedridden.

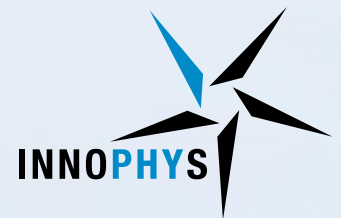
If you could continue to work without hurting your body.

If there is no hard work that can hurt your body.

If there are no caregivers or no one to be cared for.

A life should be richer.

To create such a world, we are pursuing technologies that support humans physically.



Background

Many tasks difficult to automation remained
Work-related disorders: **Lower Back pain**



Nursing care personnel



Automobile factory worker

Pneumatic McKibben artificial muscle

Light weight (< 200g)

High contraction power (2500N)

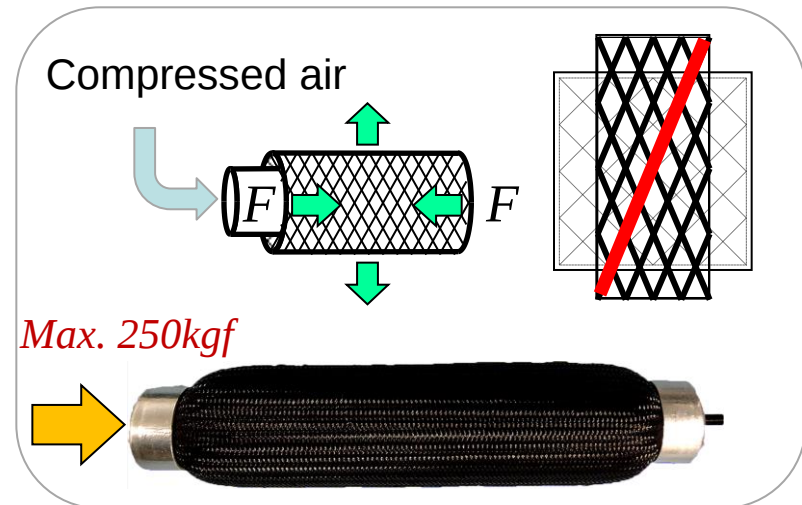
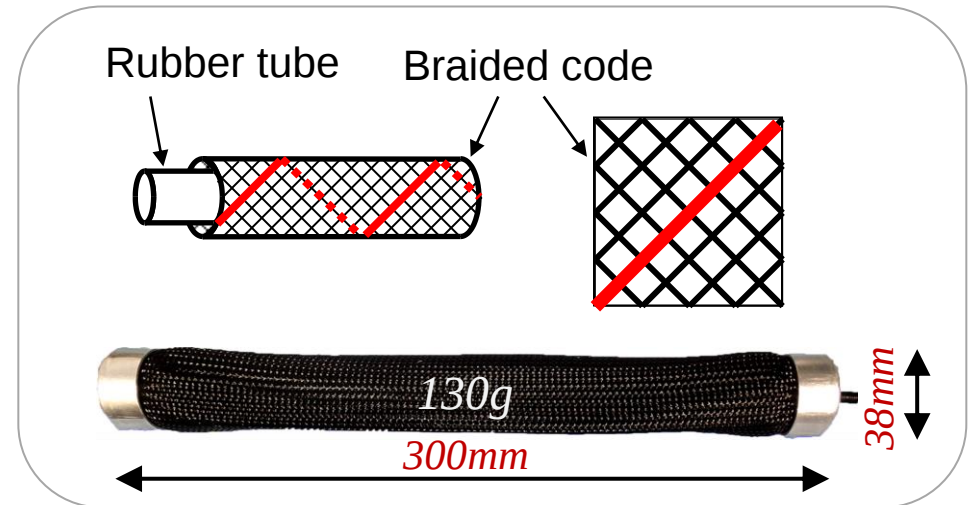
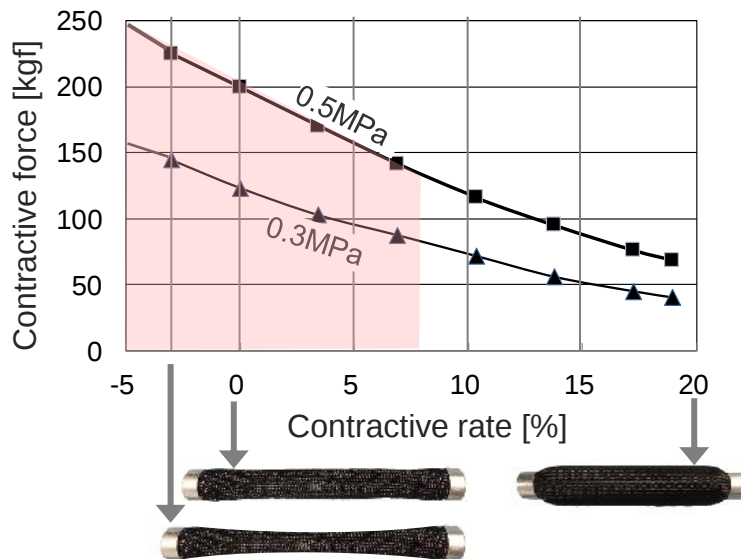
Inexpensive (< 3,000Yen=25US\$)

Simple structure

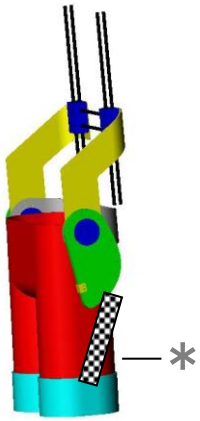
Soft material

Only contraction (<30%)

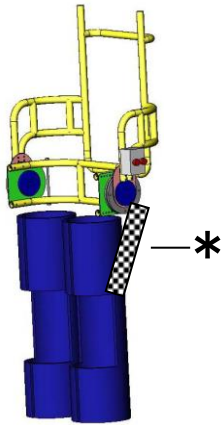
Compressed air is required



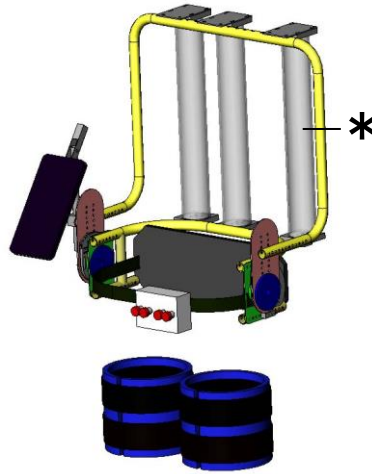
History for lower back assistance



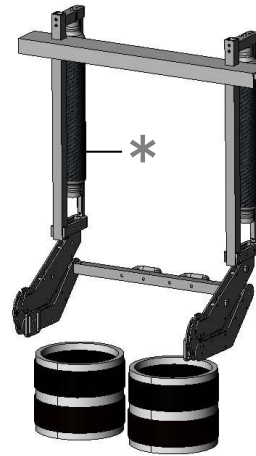
2006.11



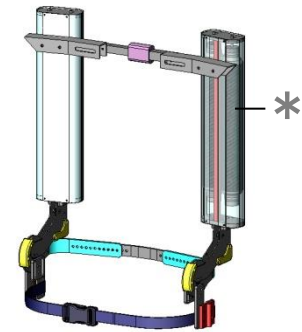
2007.1



2007.5



2008.12



2009.2



2010.3



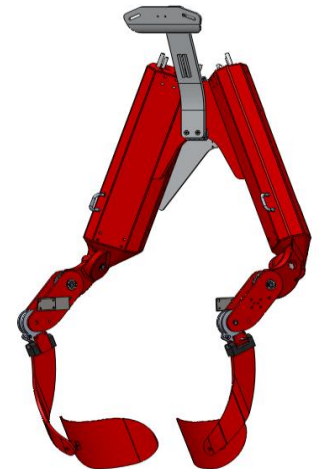
2010.7



2011.1

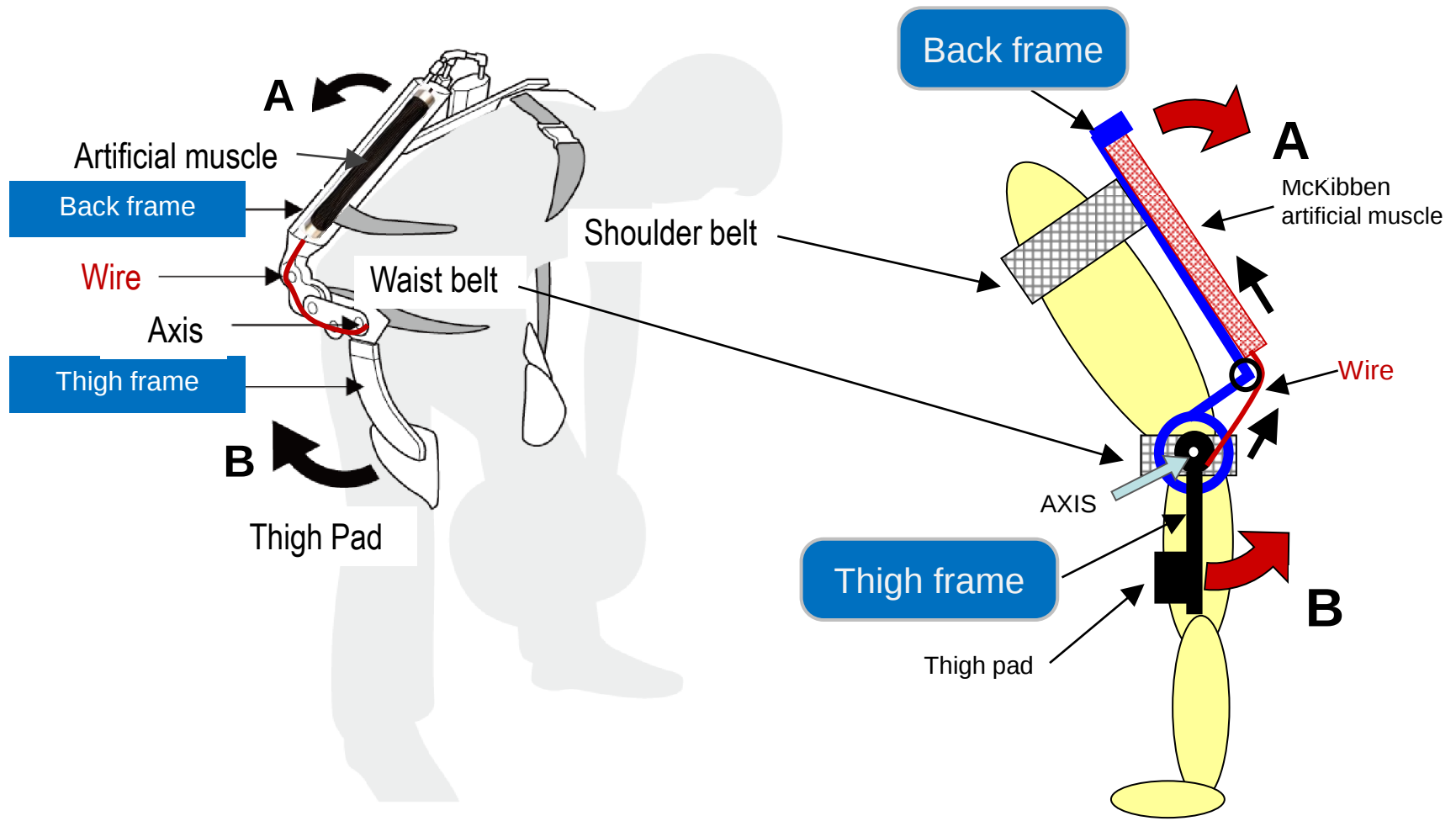


2012.1

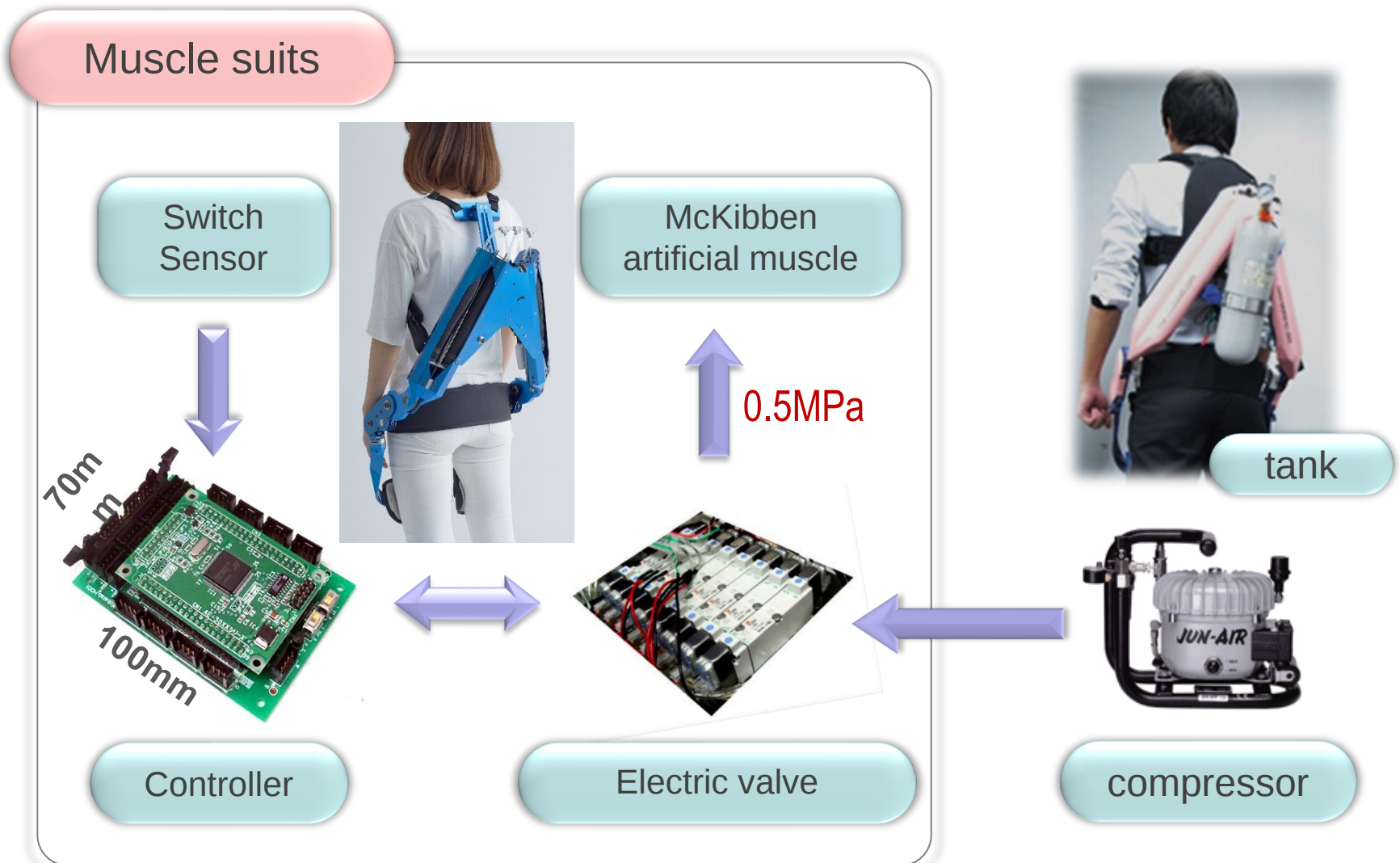


2013.1

Principle for back assistance



System configuration



Interface



Expiratory switch



Acceleration switch



Touch switch

Wearing : 10sec.



0. Loosen the belt



1. Carry on back



2. Fasten the waist belt

must be loose



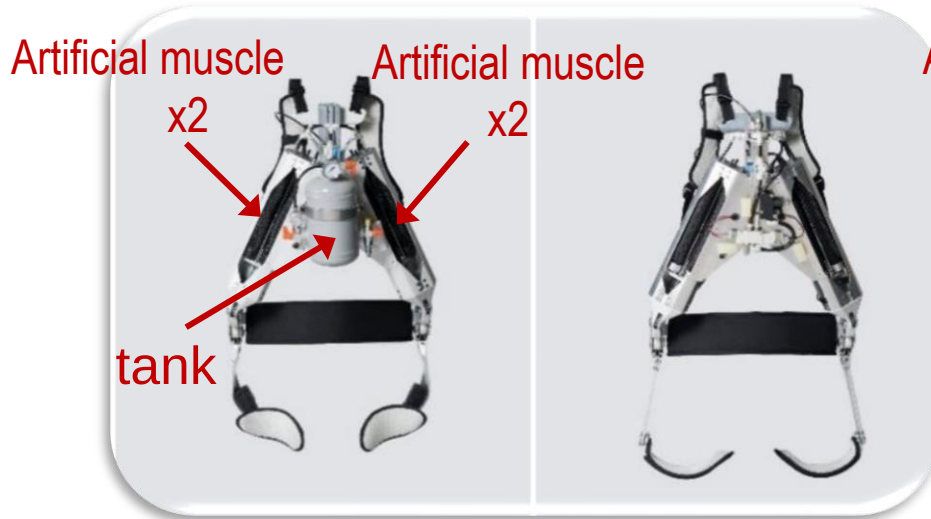
3. Fit the thigh pad



1st and 2nd model: Active type

2014

Artificial muscle x4



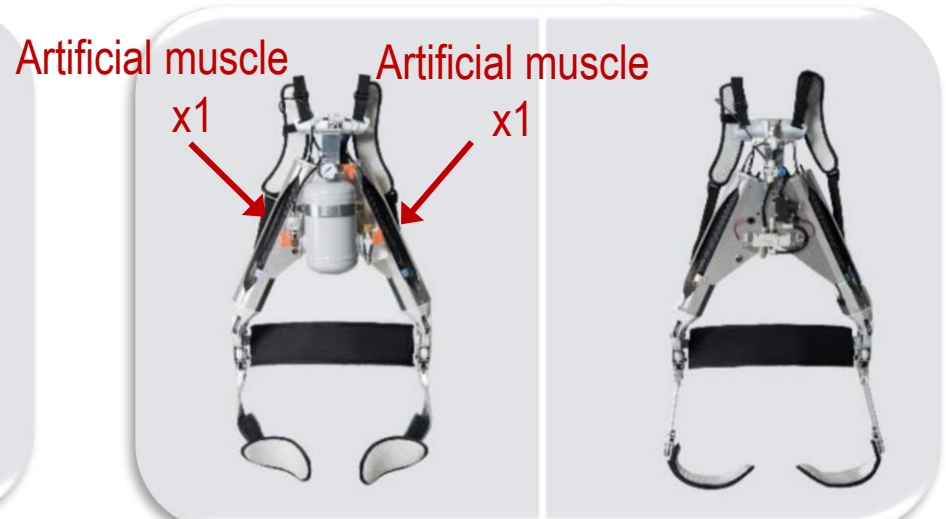
8.1kg

6.6kg

power assistance
140Nm(35.7kgf)
¥600,000
\$45,000

2015

Artificial muscle x2



6.7kg

5.2kg

power assistance
100Nm(25.5kgf)
¥600,000
\$45,000

Application: Visiting care for bath



Application: Visiting care for bath



Feedback from User

- Dislike Compressor & Tube

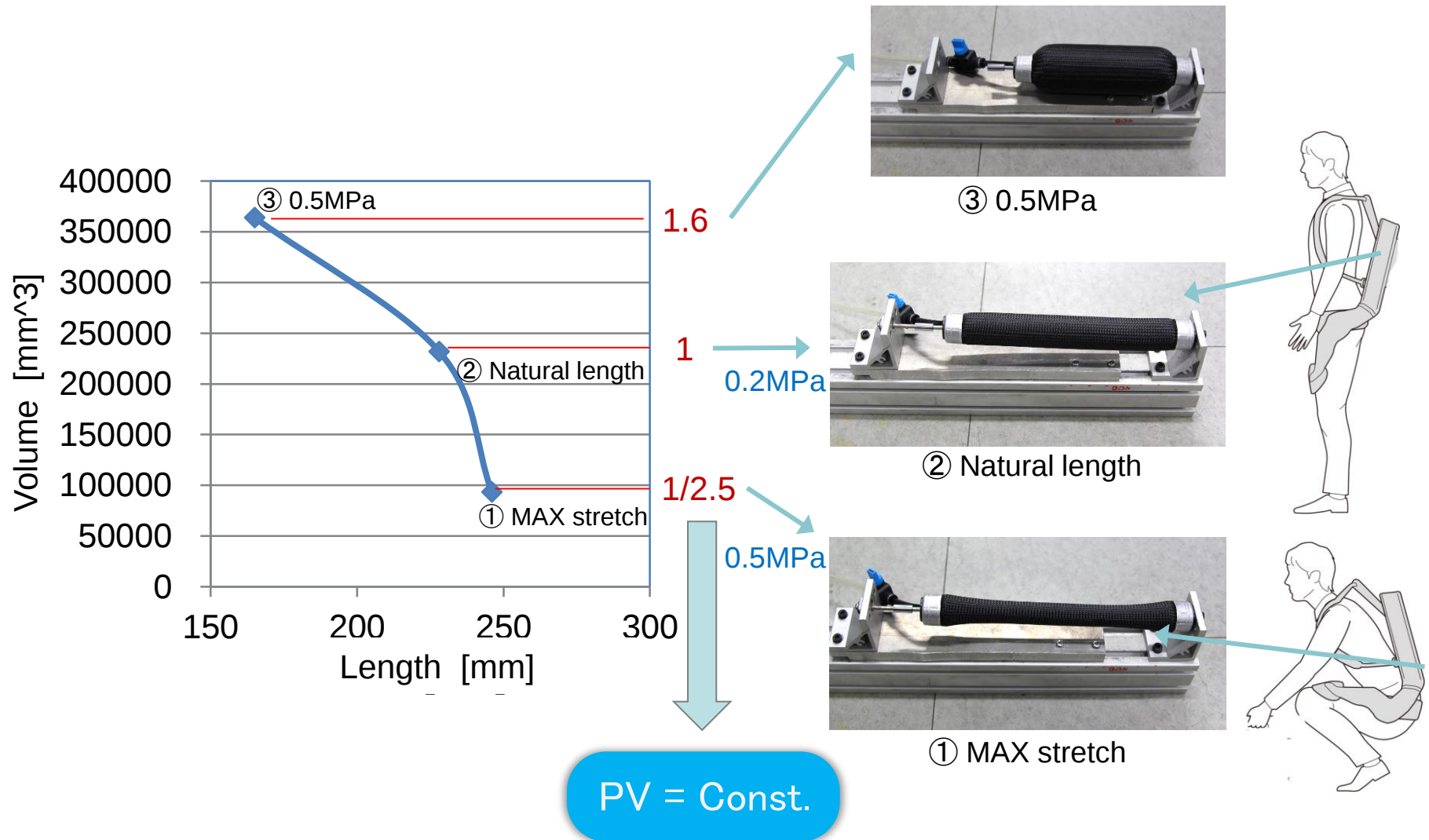


- Dislike using Interface



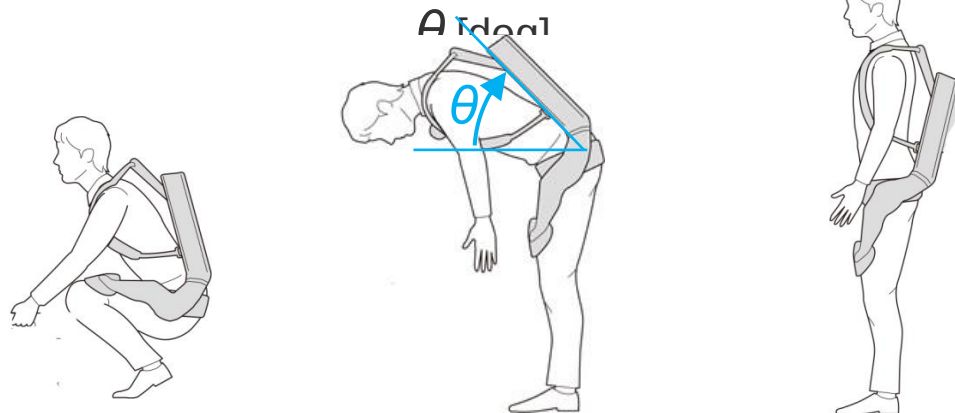
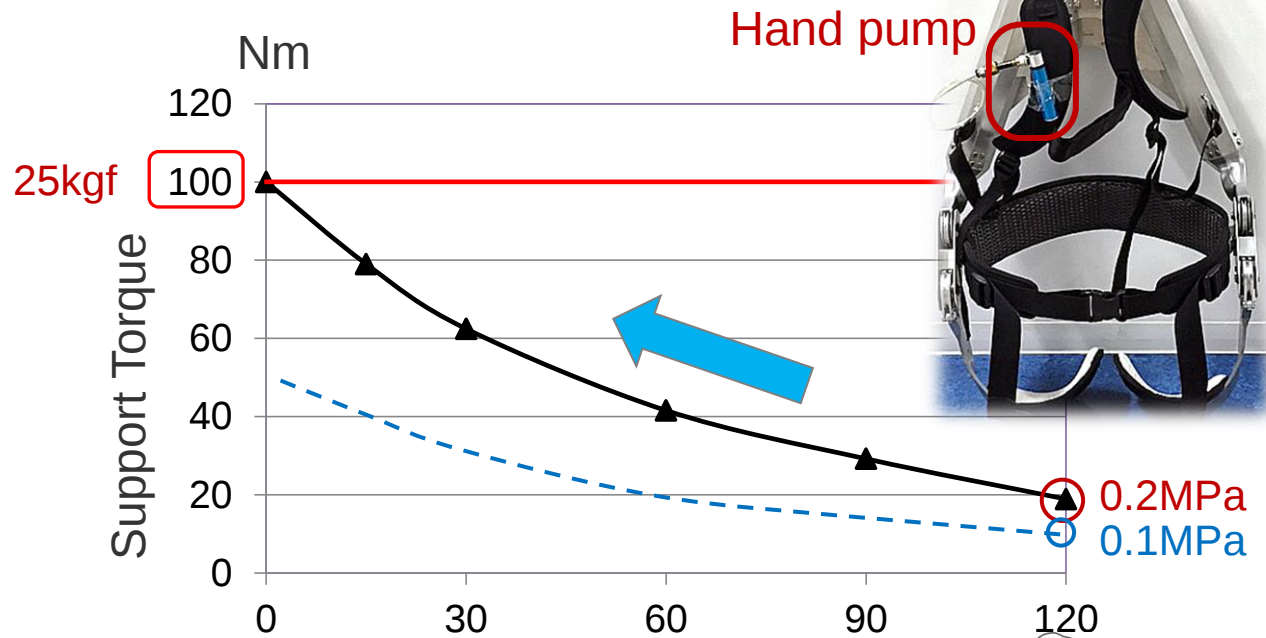
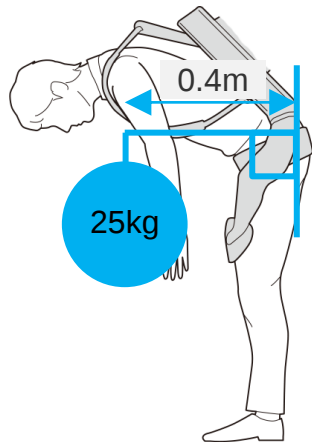
- Heavy

Length & Volume for artificial muscle



Assistance torque

$$100\text{Nm} = 25\text{kgf} \times 0.4\text{m}$$



Passive type

Hand pump



- No Compressor
- No Electricity
- No Interface
- 100Nm is realized.

Lineup of **passive** type

power assistance
100Nm(25.5kgf)

2017



5.2kg
¥700,000-800,000
\$6,000

2018

EDGE



4.3kg
¥498,000
\$4,000
4150

2019.11

EVERY



3.8kg
¥136,000
\$1,000
20,000
2021.4

Muscle suit

Active type



Compressor

Passive type



Hand pump

Industry / global expansion **passive** type

Factory



long-term care



Agriculture



construction



ASIA Taiwan
Hong Kong
China, Macau
Malaysia
Thailand

EUROPE Spain
Italy
France
Germany
Poland
Sweden
Denmark
Estonia
Latvia
Lithuania

Latin America
Mexico

Effects of **Active** type

Posture correction

Muscle suit for Rehabilitation (Function training)

Standard: **Extension Assist**

Flexion Assist

Flexion



Extension



Squatting



Standing



Flexion Assist model: ex.1

- Age: 100 years old
- 15min. training/week x 3 weeks



Flexion Assist model: ex.2

- Age: 74 years old
- Brain infarction (7 years ago)
- Left hemiplegia



- Just after 15min. Training > possible to raise left leg
- After 3 months > Walk smoothly

Flexion Assist model: ex.3

- Age: 80 years old
- Impossible to sitting straight
- Just after 15min. Training > possible
- After 3 months > Walk smoothly



Ex.5

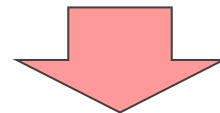
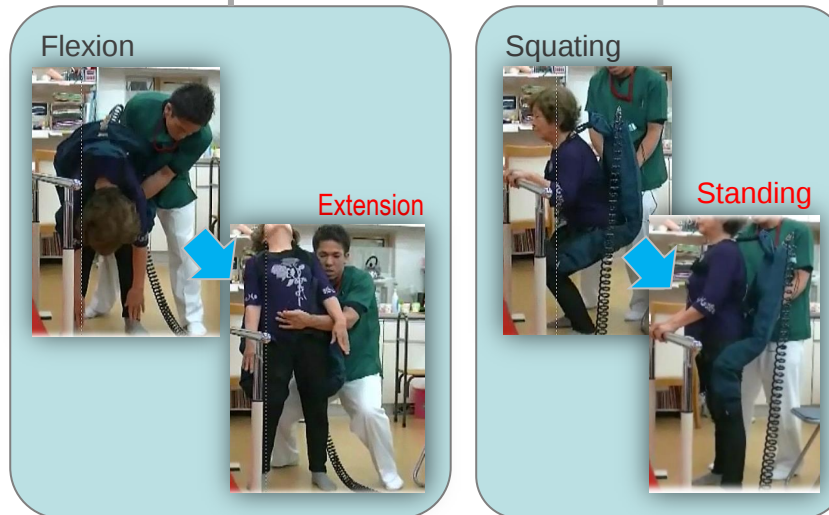
- Age 80, stroke at 40 years old



Muscle suit for Rehabilitation (Function training)

Standard: **Extension Assist**

Flexion Assist



- ◆ Hip joint position reset
- ◆ Pelvic tilt correction

Posture correction of healthy people

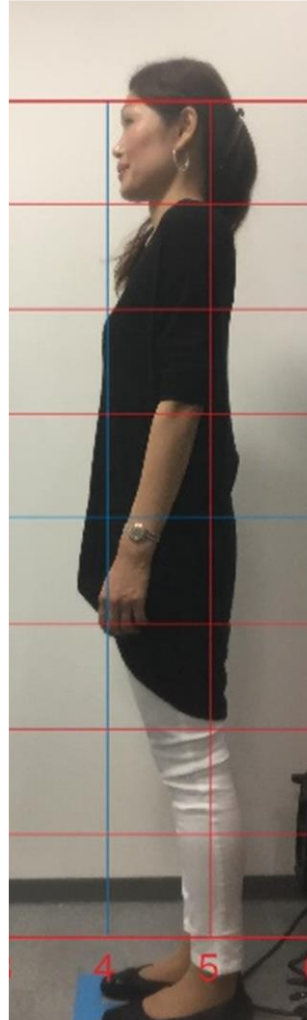


Posture correction



Before

Posture correction



After

Posture correction



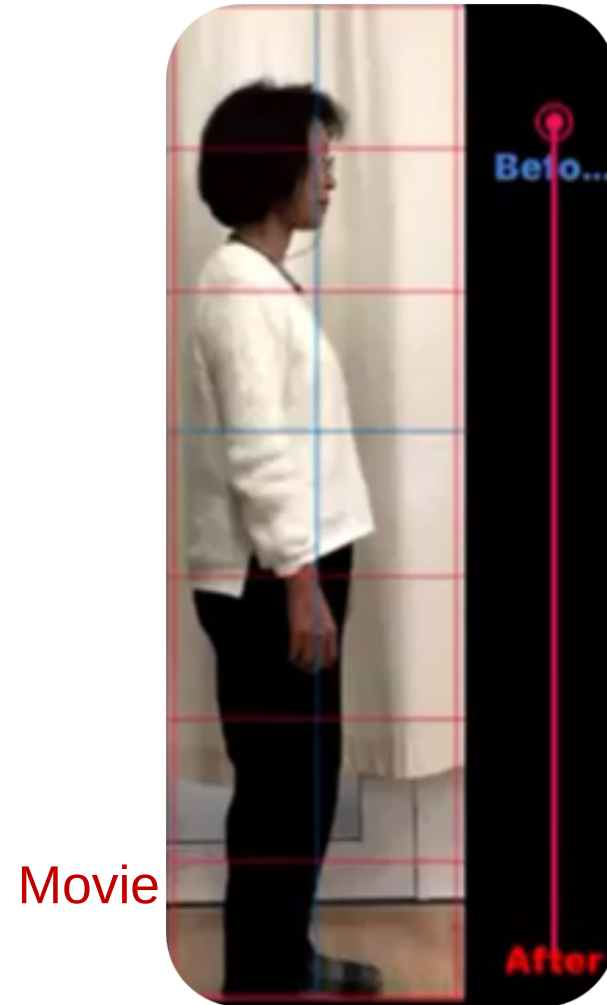
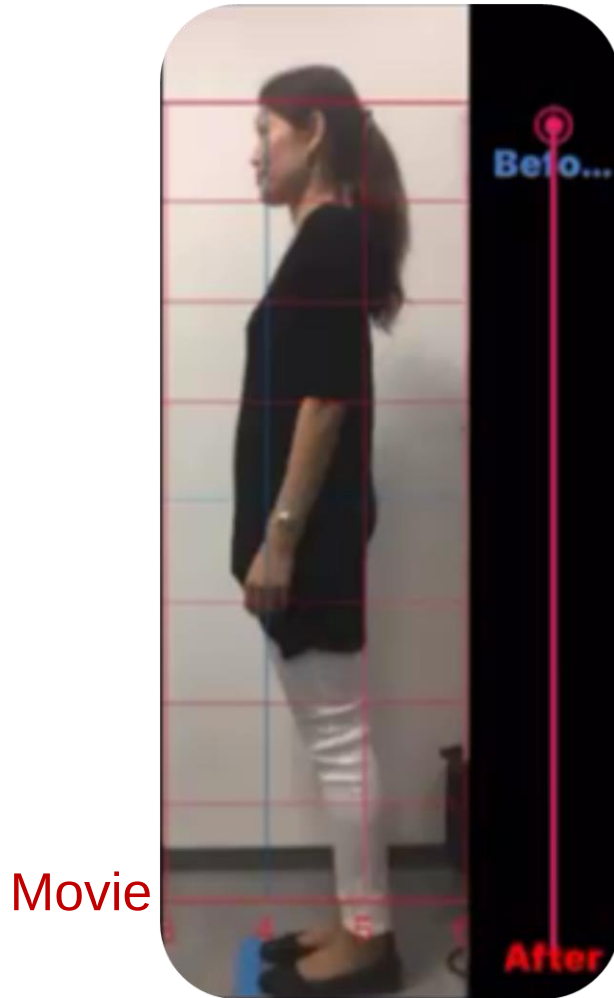
Before

Posture correction



After

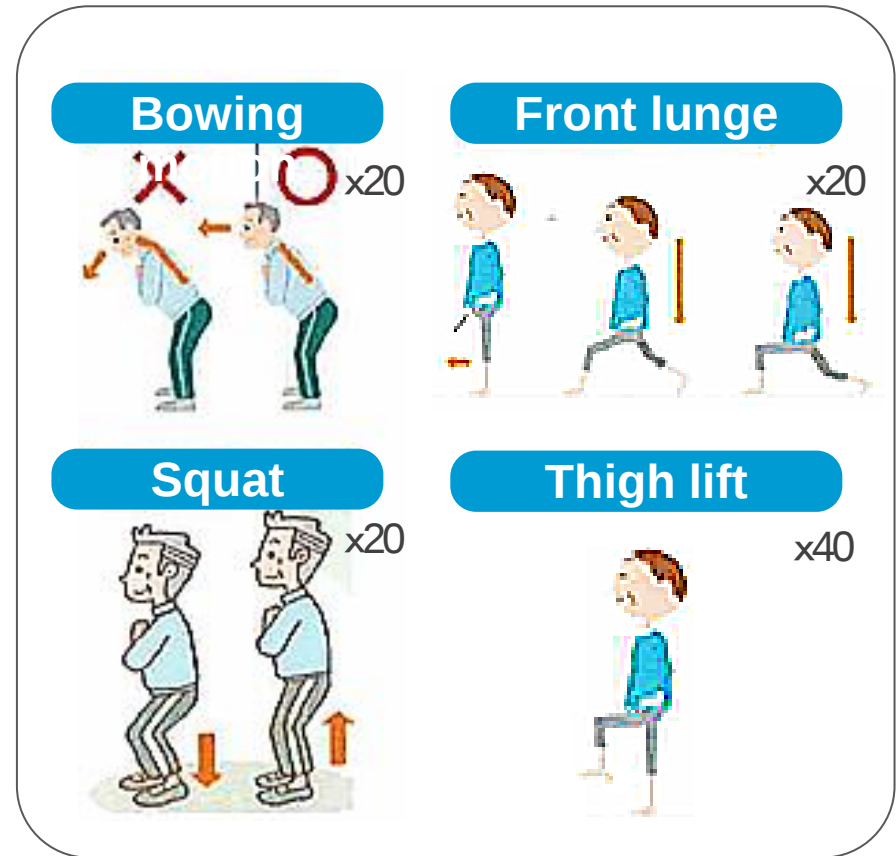
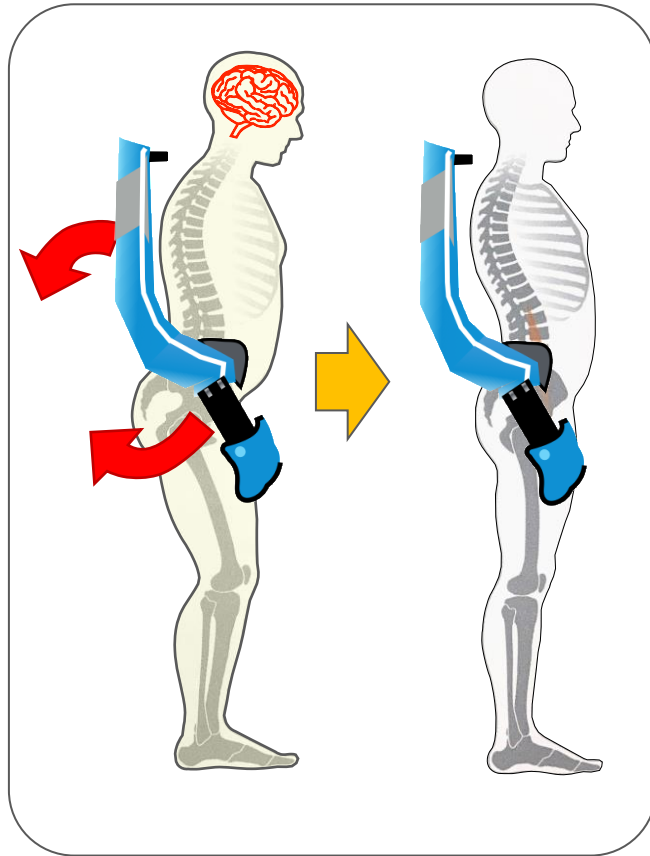
Posture correction



Effects of **Passive** type

Inner Muscle Strengthening

Passive training motion



Passive training motion



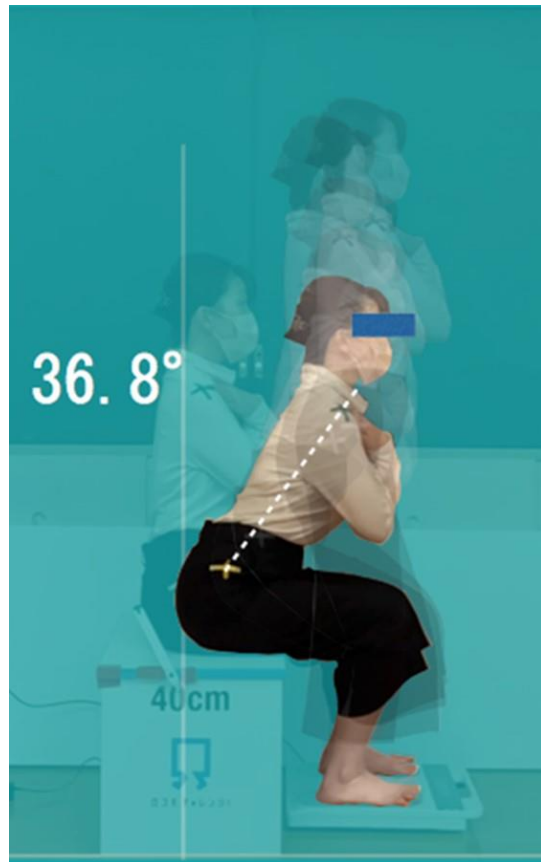
Bowing



Standing up and sitting

Passive training: Effect

Before



Ideal: 30°

After: 2 weeks



Passive training: Effect

Before



Float toes

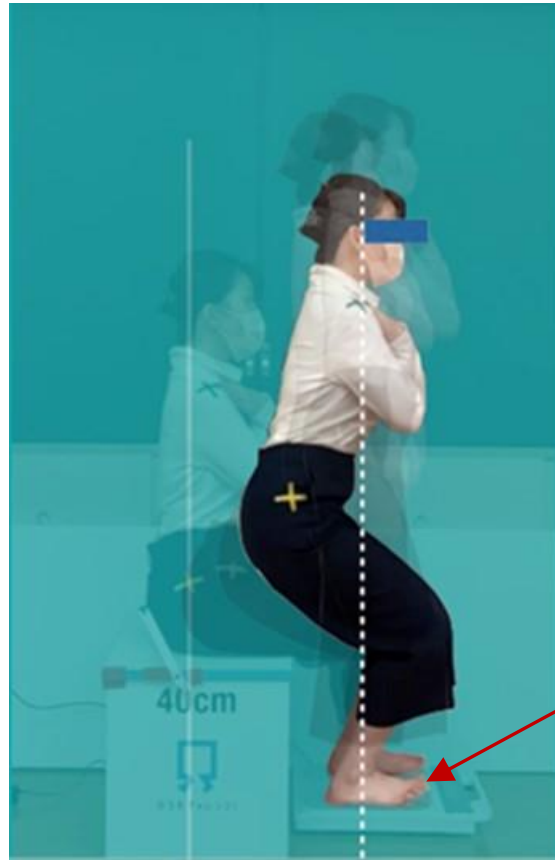
Center of gravity: Behind

After: 2 weeks



Passive training: Effect

Before



After: 2 weeks



Float toes

Center of gravity: Behind

Passive training: Effect

Before



Float toes

Center of gravity: Behind

After: 2 weeks



Passive training: Effect

Before



After: 2 weeks



Change angle → lumbar spine
pelvis

Muscle Suit

- Motion assistance
- Function training / Posture correction



,,,,,,, Thank you

Active walker for Adult: Panplegia (全麻痺) 2015

+ Consciousness disorder



Active walker for Adult: Panplegia (全麻痺) 2018



Flexion Assist model

